

K-no.: K26928

## 1700A Current Sensor for ±24V supply with a transformation ratio of $K_N=1:5000$

Date: 08.09.2021

for electric current measurement:  
DC, AC, pulsed, mixed ..., with a galvanic isolation between  
primary circuit (high power) and secondary circuit (electronic circuit)

Customer: Standard type

Customers Part no.:

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### Electrical Data – Ratings

$I_{PN}$	Primary nominal r.m.s. current	1700	A
$R_M$ <sup>1)</sup>	Measuring resistance for $I_{PN\_DC}$ @ 85°C	0 ... 30	Ω
$I_{SN}$	Secondary nominal r.m.s. or DC current	340	mA
$K_N$ <sup>2)</sup>	Turns ratio	(1): 5000	

<sup>1)</sup> for the max. measuring range depending on  $R_M$  please refer to Fig.2

<sup>2)</sup> first number in brackets represents the count of primary turns guided through the primary opening of the sensor

### Accuracy – Dynamic performance data

		min.	typ.	max.	Unit
$I_{P,max}$ <sup>1)</sup>	measuring range @ $R_M = 1 \Omega$ ; $\vartheta_A = 20^\circ C$ ; $U_C = \pm 24V$	3400			A
	@ $R_M = 1 \Omega$ ; $\vartheta_A = 85^\circ C$ ; $U_C = \pm 24V$	2750			A
X	Accuracy @ $I_{PN}$ for $\vartheta_A = 25^\circ C$			0.3	%
$X_{Ti}$	Temperature drift of X @ $\vartheta_A = -40 \dots +85^\circ C$ (secondary)			0.1	%
$\epsilon_L$	Linearity			0.1	%
$I_{SO}$	Offset current (secondary) @ $I_P = 0A$ , $\vartheta_A = 25^\circ C$			0.1	mA
$I_{SOH}$	Hysteresis current (secondary)			0.1	mA
$t_r$	Response time @ 90% of $I_{PN}$		< 0.5		μs
$\Delta t$ ( $I_{P,max}$ )	Delay time @ 10% of $I_{PN}$ (at $di/dt = 600A/\mu s$ )			0.5	μs
$f_{BW}$	Frequency bandwidth (small signal)	DC...100			kHz

<sup>1)</sup> for  $I_{P,max}$  see Fig. 1 on Page 2, short term currents with high slew rates can be measured above  $I_{P,max}$ , (transformer behavior)

### General data

		min.	typ.	max.	Unit
$\vartheta_A$ <sup>1)</sup>	Ambient operating temperature	-40		+85	°C
$\vartheta_S$	Ambient storage temperature acc. VAC M3101	-45		+100	°C
m	Mass		550		g
$U_C$	Supply voltage	±22.8	±24	±25.2	V
$I_{CO}$	Current consumption for $I_P = 0A$		±31		mA
$I_{CN}$ <sup>2)</sup>	Current consumption for $I_{PN} = 1500A$	270	310	375	mA

<sup>1)</sup> The temperature of the sensor surface at any position must not exceed 105°C

<sup>2)</sup> Due to the Class-D final stage used for generating the compensation current, the supply current  $I_{CN}$  ( $I_C$  @  $I_P = I_{PN}$ ) is lower than  $I_{SN}$ .  
The specified wide range of the supply current is reasoned by dependencies on ambient operating temperature  $\vartheta_A$  and the value of the resistor  $R_M$  connected to the sensor output.

$S_{clear}$ <sup>3)</sup>	Clearance distance	22			mm
$S_{creep}$ <sup>3)</sup>	Creepage distance	22			mm
$U_{sys}$ <sup>3)</sup>	System voltage			1000	$V_{RMS}$
				3127	$V_{RMS}$
$U_{sys}$ <sup>3)</sup>	Working voltage			1000	$V_{RMS}$
				4400	$V_{RMS}$
$U_{PD}$ <sup>3)</sup>	Rated discharge voltage			1414	$V_{PEAK}$
	Maximum potential Difference acc. to UL 508			1000	$V_{RMS}$

<sup>3)</sup> Constructed and manufactured and tested in accordance with IEC 61800-5-1:2007 (secondary pins 1, 2 and 3 to primary opening)  
Insulation material group 1, Pollution degree 2, Overvoltage category III, altitude ≤ 2000m

Date	Name	Issue	Amendment
		81	

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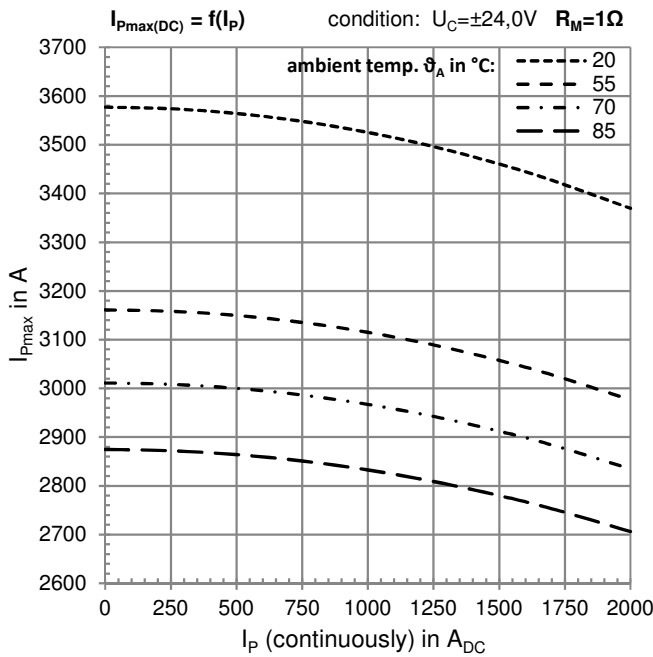
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**Measurement Range Derating**

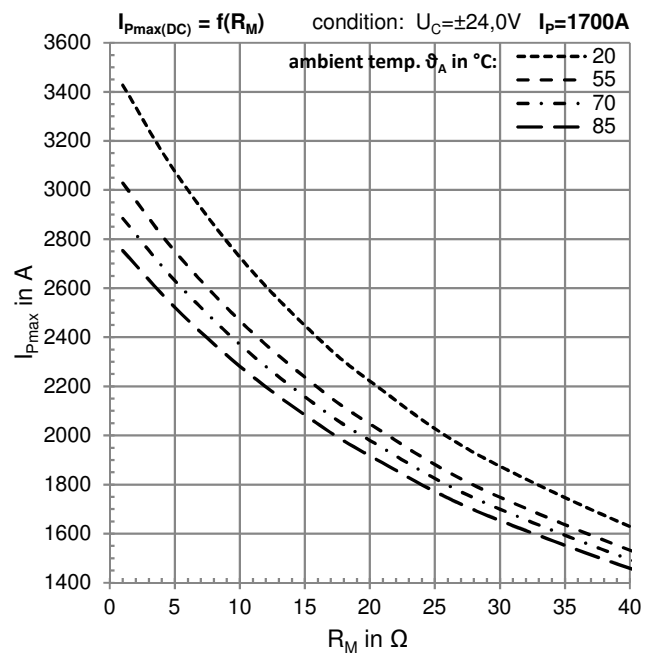
In addition to the sensor design and construction, following operating parameters have high influence to the measurement range limit  $I_{Pmax}$ : the actual continuous primary current  $I_P$ , the burden resistor  $R_M$ , the ambient temperature  $\vartheta_A$ , the supply voltage  $\pm U_C$  and the busbar temperature. (following curves are interpolated calculations verified by sample measurements)

**Derating depending on primary current  $I_P$ :**



**Fig. 1:** measureable current  $I_{Pmax}$  depending on the primary continuous current  $I_P$

**Derating depending on connected burden resistor  $R_M$ :**



**Fig. 2:** measureable currents  $I_{Pmax}$  depending on the burden resistor  $R_M$

**Dwell Time Limits For Maximum DC Currents ( $I_{Pmax}$ )**

$\vartheta_A$	ambient temperature	85			°C
$R_M$	burden resistor	1	5	10	Ω
$I_{Pmax(DC)}$	max. DC primary current	2750	2500	2260	A
$t_{dwell}$	<b>Permissible dwell time for <math>I_{Pmax(DC)}</math></b>	<b>&lt; 4</b>	<b>&lt; 6</b>	<b>&lt; 8</b>	<b>minutes</b>

**Tab.1:** permissible dwell times for measureable DC peak currents at 85°C without degradation of the sensor expected

after higher current loads ( $I_P > I_{PN}$ ) recovery times should be taken into account.

**Absolute Maximum Ratings For Continuous Currents\***

$\vartheta_A$	≤ 85°C
$R_M$	≥ 1Ω
$I_P$ continuous	≤ 1800A <sub>DC</sub>

\* Exposure to this absolute maximum conditions for extended periods may degrade device reliability and lifetime. Stresses above these ratings may cause permanent damage. These are stress ratings. Functional operation of the device at these or any other conditions beyond those specified is not supported. This conditions don't comply with UL-Certification.

**Tab.2:** absolute maximum ratings for continuous currents with not to be excluded degradation and without UL-compliance

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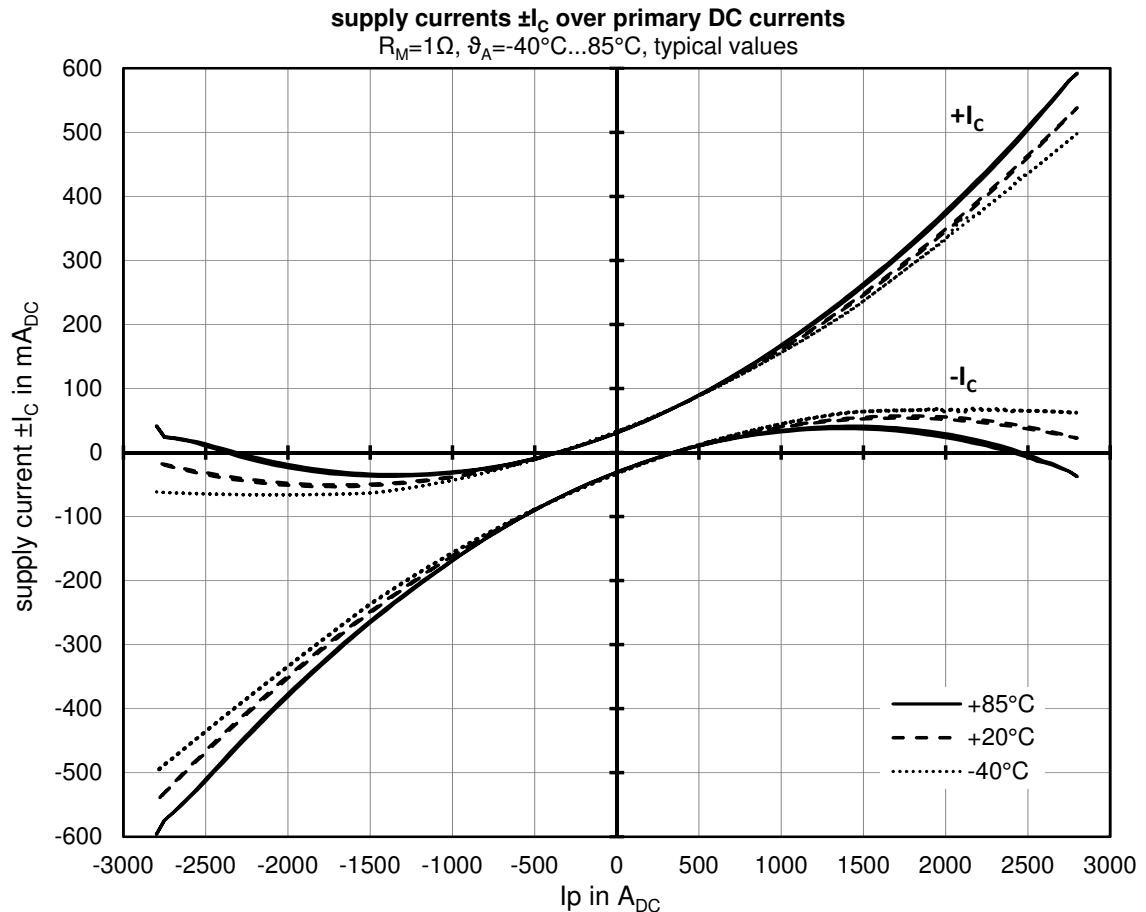
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**Supply Current Consumption**



**Fig. 5:** supply current consumption ( $\pm I_c$ ) at positive and negative supply voltage over primary current

Background information: "bus pumping effect"

For DC and low frequency measurements the output current of the sensor (or so called compensation current) is generated by a class D switching amplifier. the advantages of this technology are low power losses, meaning low self-heating of the sensor what makes a continuous measurement of high primary currents possible. Due to the principle of this technology, for  $I_P > +300A$  the negative supply current  $I_c-$  is getting positive and vice versa for  $I_P < -300A$  the positive supply current  $I_c+$  is getting negative as shown in Fig. 5. This effect reaches a maximum/minimum at a certain primary current depending on the operating temperature and the connected burden resistor  $R_M$ . It decreases by an increase of  $R_M$  or the operating temperature.

- reverse supply currents of the sensor can be used supply (partially) other loads connected to the same power supply
- sensors in three phase systems, where all sensors are connected to one power supply, the supply currents of the sensors can compensate each other similar to the behaviour of load currents in the star point of a three phase system (vector addition).

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**Noise And Offset Ripple Reduction**

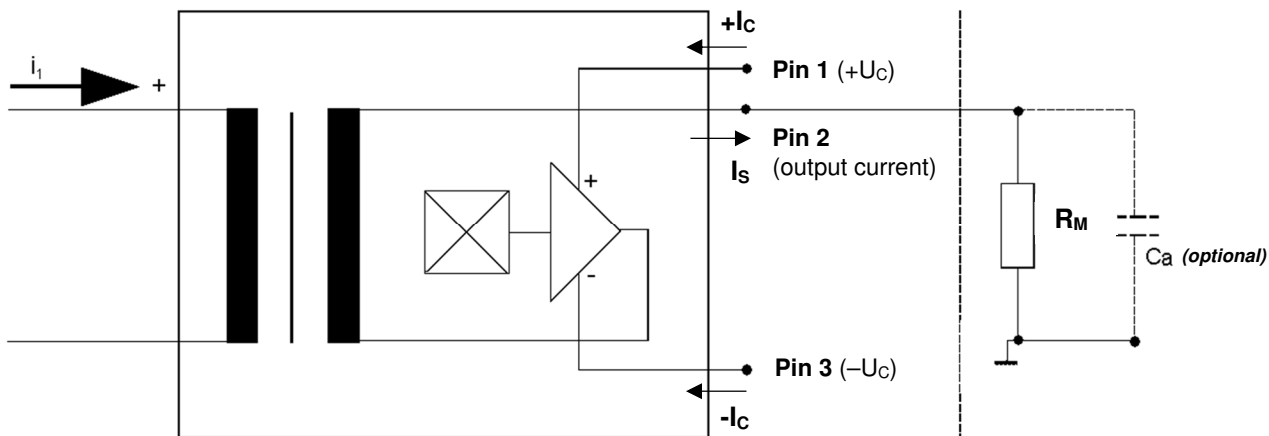
The offset ripple and noise can be reduced by an external low pass. The simplest solution is a passive low pass filter of 1st order with

$$f_g = \frac{1}{2\pi \cdot R_M \cdot C_a}$$

In this case the response time is enlarged. It is calculated from:

$$t'_r \geq t_r + 2.5R_M C_a$$

**Connection diagram**



*for information regarding connector type and pin assignment please refer to section „mechanical drawing“*

**Fig. 6:** simplified schematic diagram of the sensor

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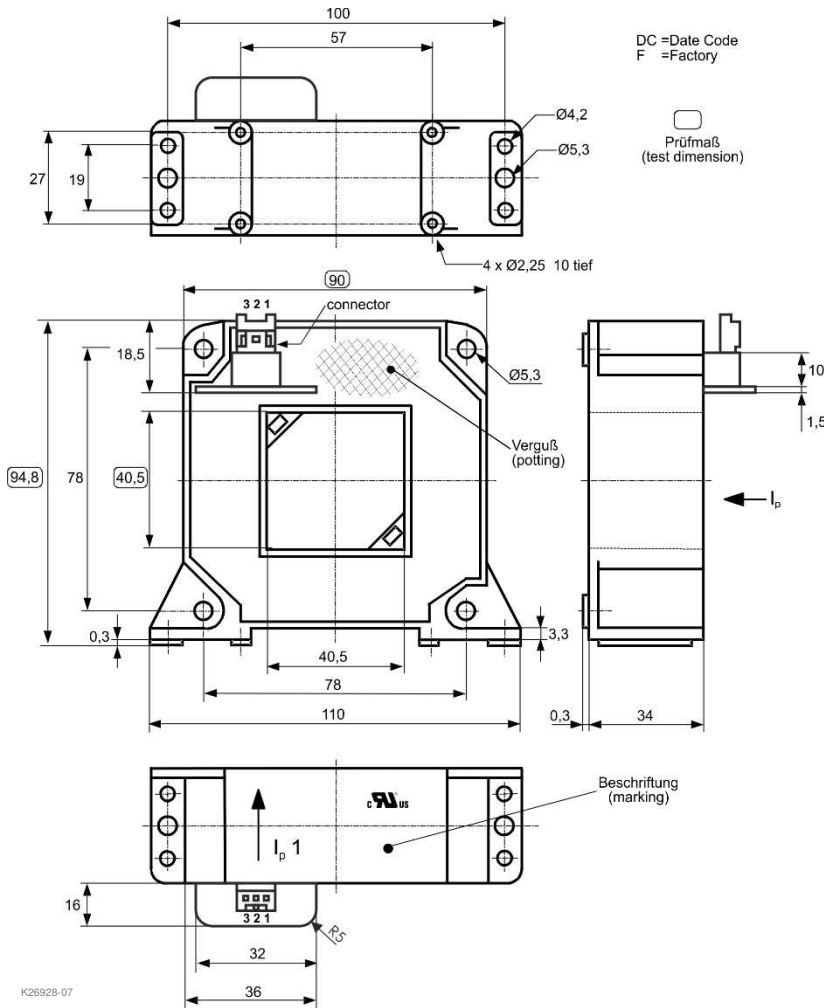
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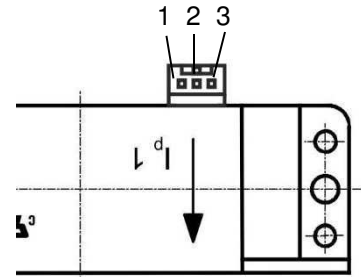
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### Mechanical outline (mm):

General tolerance DIN ISO 2768-c



### Connector:

**JST B03B-XASK-1**


### Pin Assignment:

- Pin 1: +U<sub>c</sub>
- Pin 2: I<sub>s</sub>
- Pin 3: -U<sub>c</sub>

### Marking

Explanation: Item number: see Tab.2 (left column)

- F = Factory code
- DC = Date code (YWW)

Arrow shows positive current direction

VAC Logo UL Logo (will follow)


**Example: Sensor with end number X256**

- Produced in Slovakia in CW38 2018
- Part number: 4640-X256
- Factory code: SK
- Date code: K38


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**Datamatrix Code specification**



Code Size:

metrical size: 18mm x 18mm

symbol size: 24 x 24 points

(additionally with a quite zone around the data area)

Code Content:

Standard: ANSI MH10.8.2

1T“Batch-no.”@1P“Item-no.”@2P“datasheet revision”@6D“datecode”@10V“production site”

1T0001234567@1PT60404-P4640-X256@2P81@6DK36@10VSK

**Routine Test**

Measurement after temperature balance of the samples at room temperature; SC = significant characteristic

$K_N(N_1/N_2)$	(100%) M3011/6	Transformation ratio ( $I_P=1500A$ , 40-80 Hz)	1 : 5000 $\pm$ 0.3	% (SC)
$I_{SO}$	(100%) M3226	Offset current	< 0.1	mA
$U_P$	(100%) M3014	Test voltage (1s) Pin 1,3,5 to primary opening	2.2	kV <sub>RMS</sub>
$U_{PDE}$	(AQL 1/S4)	Partial discharge voltage (extinction)	1500	V <sub>RMS</sub>
$U_{PD(rms)}$ · 1.875		*acc. table 24	2813	V <sub>RMS</sub>

**Type Test**

Preconditioning acc. VAC M3236 (Pin 1,3,5 to primary opening)

$\dot{U}_W$	M3064	HV transient test (1.2 $\mu$ s / 50 $\mu$ s, 5 pulses $\rightarrow$ polarity +, 5 pulses $\rightarrow$ polarity -)	12	kV
$U_P$	M3014	Test voltage (5s)	4.4	kV <sub>RMS</sub>
$U_{PDE}$	M3024	Partial discharge voltage (extinction)	1500	V <sub>RMS</sub>
$U_{PD(rms)}$ · 1.875		*acc. table 24	2813	V <sub>RMS</sub>

\* IEC61800-5-1:2007

**Applicable documents and standards**

Constructed, manufactured and tested in accordance with IEC61800-5-1:2007.

Further standards: UL 508; file E317483, category NMTR2 / NMTR8

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### Explanation of the terms used in the datasheet

$I_{SN}$ : Nominal secondary current (secondary current value at  $I_{PN}$ )

$X_{total}(I_{PN})$ : The sum of all possible errors over the temperature range by measuring a current  $I_{PN}$ :

$$X_{total} = 100 \cdot \left| \frac{I_S(I_{PN})}{K_N \cdot I_{PN}} - 1 \right|$$

$X$ : Permissible measurement error in the final inspection at RT.  
 $I_{SB}$  is the DC output current for a DC primary current with the same value as the (positive) rated current  $I_{PN}$  (with  $I_O = 0$ )

$$X = 100 \cdot \left| \frac{I_{SB}}{I_{SN}} - 1 \right|$$

$X_{Ti}$ : Temperature drift of the rated value orientated output term.  
 $I_{SN}$  (cf. Notes on  $F_i$ ) in a specified temperature range:  
 $I_{SB}$  is the secondary current at temperature  $\vartheta_{A1}$  or  $\vartheta_{A2}$

$$X_{Ti} = 100 \cdot \left| \frac{I_{SB}(\vartheta_{A2}) - I_{SB}(\vartheta_{A1})}{I_{SN}} \right|$$

$\epsilon_L$ : Linearity fault where  $I_P$  is any input DC and  $I_{Sx}$  the corresponding output term. ( $I_O = 0$ ).

$$\epsilon_L = 100 \cdot \left| \frac{I_P}{I_{PN}} - \frac{I_{Sx}}{I_{SN}} \right|$$

### Offset, hysteresis and drift

$I_{SO}$ : Offset current

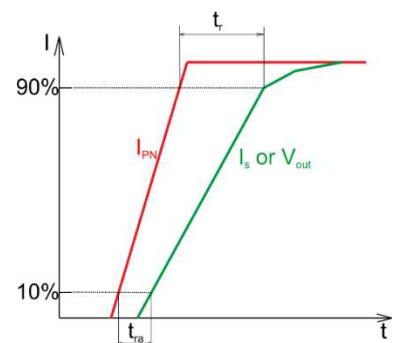
$I_{SOH}$ : hysteresis offset at  $I_P=0A$ , meaning secondary current after overloading the sensor by a direct current of  $3 \cdot I_{PN}$  with  $R_M=100\Omega$

$I_{Oi}$ : Long term drift of  $I_O$  after 100 temperature cycles in the range -40 to 85 °C.

### Dynamic properties

$\Delta t(I_{P,max})$ : delay time between a rectangular primary current and the output current  $I_S$  at  $I_P = 0.1 \cdot I_{PN}$

$t_r$ : Response time, measured as a delay time between a rectangular primary current and the output current  $I_S$  at  $I_P = 0.9 \cdot I_{PN}$



### Voltage ratings (according to IEC 61800-5-1:2007)

$U_{PD}$  Rated discharge voltage (recurring peak voltage separated by the insulation)

$U_{sys}$  System voltage: RMS value of rated voltage

$U_{AC}$  Working voltage: RMS voltage which occurs by design in a circuit or across an insulation

$U_{ACP}$  Working voltage recurring peak voltage acc. IEC 61800-5-1 which occurs by design in a circuit or across insulation.

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